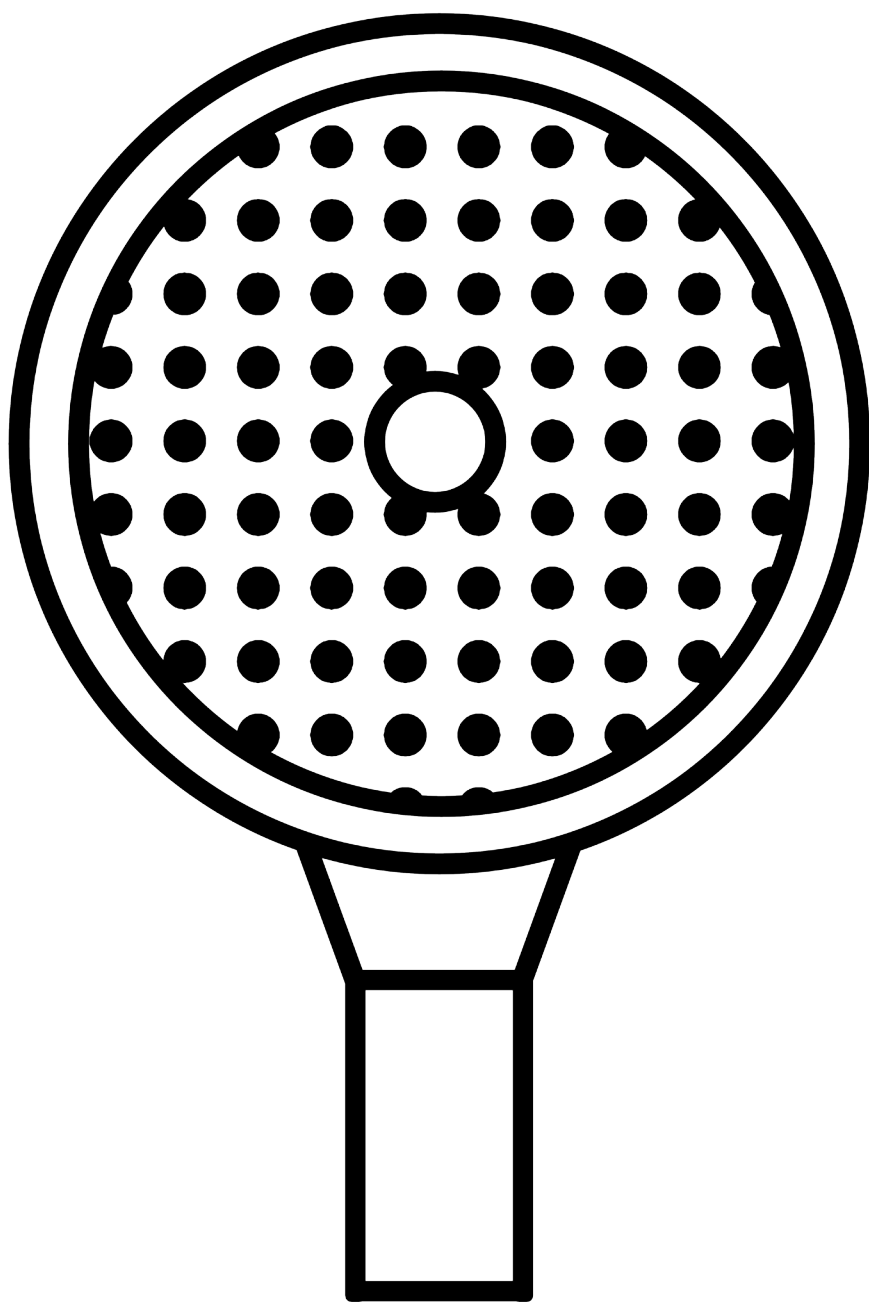
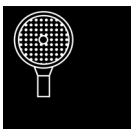


# Encoder









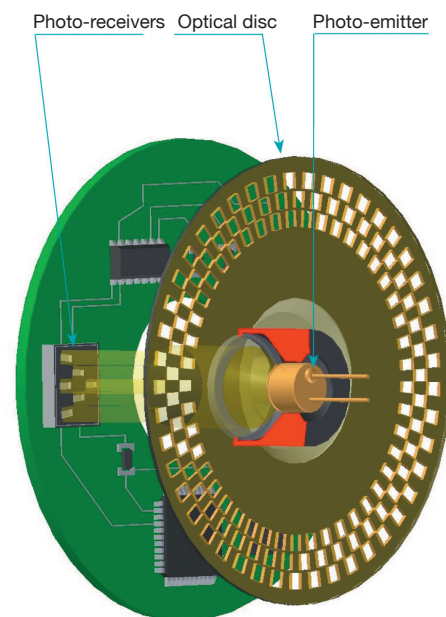
# Encoder

## Basic theory



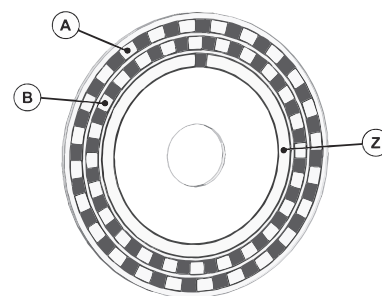
### Working principle

An encoder is a rotary transducer that converts an angular movement into a series of electrical digital pulses. If associated to racks or endless screws, these generated pulses can be used to control angular or linear movements. During rotation, electrical signals can be elaborated by numerical controls (CNC), programmable logic controls (PLC), control systems, etc. Main applications of these transducers are: machinery, robots, motor feedback, measure and control devices. In M.D. Micro Detectors encoders the angular movement transduction is based on the photo-electric scanning principle. The reading system is based on the rotation of a radial graduated disk formed by opaque windows and transparent ones alternated. The system is perpendicularly illuminated by an infrared light source. The light projects the disk image on the receivers surface which are covered by a grating called collimator having the same disk steps. The receivers transduce the occurring light variations caused by the disk shifting and convert them into their corresponding electrical variations. Electrical signals, raised to generate squared pulses without any interference, must be electronically processed. The reading system is always carried out in differential modality, that is comparing different signals nearly identical but out of phase of 180 electrical degrees. That in order to increase quality and stability of output signals. The reading is performed comparing the difference between the two channels, to remove the noise known as "common mode", because signals are overlapped in equal way on each wave.



### Incremental encoder

The incremental encoder usually gives two types of squared waves out of phase of 90 electrical degrees. They are usually called channel A and B. The first channel gives information about the rotation speed while the second, basing on the state sequence produced by the two signals, provides the direction of rotation. A further signal, called Z or zero channel, is also available. It gives the absolute zero position of the encoder shaft. This signal is a squared pulse with phase and width centered on A channel.



The incremental encoder accuracy depends on mechanical and electrical factors. These errors could be: grating division, disk eccentricity, bearings eccentricity, electronic reading and optical inaccuracy. The measurement unit to define encoder accuracy is the electrical degree. It determines the division of the impulse generated by the encoder: 360 electrical degrees correspond to the mechanical rotation of the shaft which is necessary to carry out a complete cycle. To know how many mechanical degrees correspond to 360 electrical degrees the following formula has to be applied:

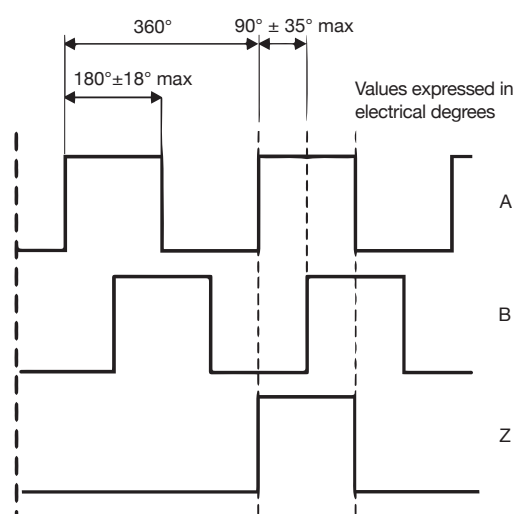
$$\text{electrical } 360^\circ = \frac{\text{mechanical } 360^\circ}{\text{nr. pulses / turn}}$$

The encoder division error is given from the maximum shifting shown in the electrical degrees of two consecutive edges. This error exists in any encoder and is due to the above mentioned factors.

On M.D. Micro Detectors encoders pulse error is  $\pm 18^\circ$  e max. on full operating range, which corresponds to a  $\pm 10\%$  from nominal value.

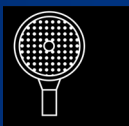
Regarding the 90 electrical degrees phase relation between the two channels, it differs in  $\pm 35$  electrical degrees max which corresponds to  $\pm 10\%$  respect to signal period.

CLOCKWISE ROTATION DIRECTION



Graphic representation of A, B and Z incremental signals.





# MDI 40 A series

Miniaturized ø 42 mm encoder series for general factory automation applications



Miniaturized Ø42 mm encoder

## features

- 3 channel encoder (A / B / Z) up to 2500 ppr
- Power supply up to +30 VDC with several electronic outputs available
- Up to 220 kHz output frequency
- Cable output, connectors available on cable end
- 6 mm solid shaft diameter
- Mounting by clamping flange



## web contents



- Application notes
- Photos
- Catalogue / Manuals



## code description

	MDI	40A	500	Z	5/30	L	6	X	X	P	R
series	MDI	incremental encoder series MDI									
model	40A	clamping flange ø 20 mm									
resolution	D	ppr 100 ... 2500 mm									
zero pulse	S	without zero pulse									
	Z	with zero pulse									
power supply	5/30	5...30 Vdc									
electronic interference	P	push-pull									
	L	line driver									
shaft diameter	6	6 mm									
enclosure rating	X	IP54									
	S	IP66									
option	X	to be reported									
output type	P	cable (standard length 0.5 m)*									
direction type	R	radial									

\* Longer cable available on demand



## technical specifications

	MDI 40
shaft diameter	ø 6 mm
IP mechanical protection	X = IP 54 (IEC 60529) S = IP 66 (IEC 60529)
max rotation speed	3000 rpm (IP 66) 6000 rpm (IP 54)
max shaft load	5 N axial / radial
shock resistance	50 G, 11 ms (IEC 60068-2-27)
vibration resistance	10 G, 10 ... 2000 Hz (IEC 60068-2-6)
moment of inertia	0,1 x 10 <sup>-6</sup> kgm <sup>2</sup>
starting torque (at +20°C / +68°F)	< 0,01 Nm (IP 54) < 0,05 Nm (IP 66)
body material	EN-AW 2011 aluminum
shaft material	1.4305 / AISI 303 stainless steel
housing material	PA66 glass fiber reinforced
bearings	2 ball bearings
bearings life	10 <sup>9</sup> revolutions
operating temperature	-25° ... +85°C (-13° ... +185°F)
storage temperature	-25° ... +70°C (-13° ... +158°F)
weight	100 g (3,52 oz)
resolution	from 100 to 2500 ppr
power supply	5/30 = 4,5 ... 30 V DC (reverse polarity protection)
No-Load supply current	800 mW
max load current	20 mA / channel
output type*	push-pull / line driver
max output frequency	220 kHz
counting direction	A leads B clockwise (shaft view)
EMC	IEC 61000-6-2 IEC 61000-6-4

\* output levels according to power supply



function	Cable output Push pull	Cable output Line driver
+V DC	red	red
0 V	black	black
Ch. A	green	green
Ch. A-	/	brown
Ch. B	yellow	yellow
Ch. B-	/	orange
Ch. Z	blue	blue
Ch. Z-	/	white
⏏	shield	shield

resolutions

MDI 40 A
100* - 120 - 128 - 150* - 200* - 240 - 250 - 256 - 300* - 360* - 400* - 480 - 500* - 512* - 600* - 625 - 720* - 750 - 800 - 900 - 1000* - 1024* - 1200* - 1250 - 1440* - 1500 - 1600 - 1800 - 2000* - 2048* - 2500

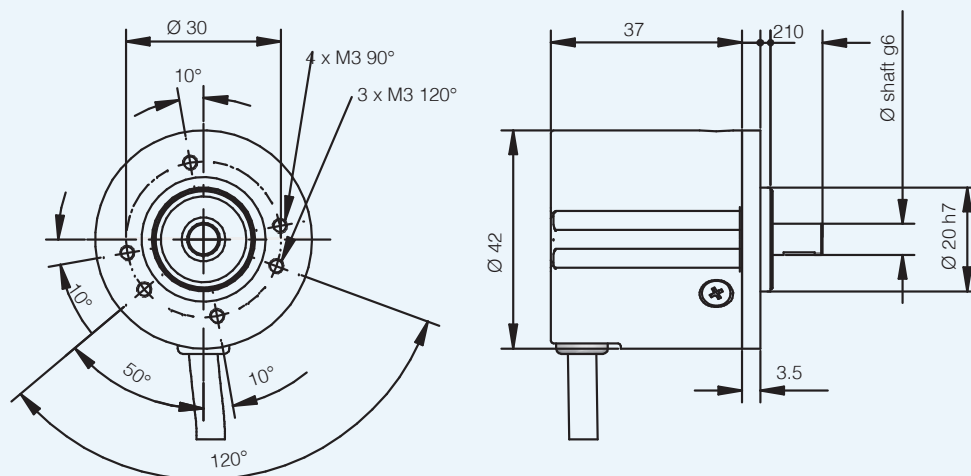
\* preferred resolutions



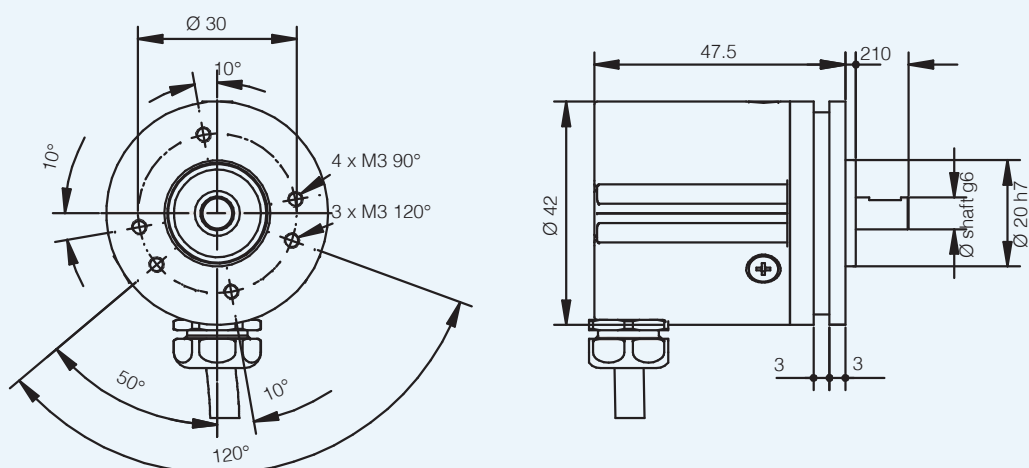
## dimensions (mm)

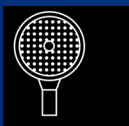
Miniaturized Ø42 mm  
encoder

MDI 40 A IP54



MDI 40 A IP66





# MDI 58 B / C series

Standard Ø 58 mm encoder series for industrial applications with high mechanical resistance requirements



Standard Ø 58 mm  
encoder

## features

- 3 channel encoder (A / B / Z) up to 2500 ppr
- Power supply up to +30 VDC with several electronic outputs available
- Up to 220 kHz output frequency
- Cable or connector output
- Solid shaft diameter up to 10 mm
- Mounting by synchronous, clamping flange



## web contents



- Application notes
- Photos
- Catalogue / Manuals



## code description

	MDI	58B	1000	Z	5/30	P	6	X	X	P	R
series	MDI	incremental encoder series MDI									
model	58B	synchronous flange Ø 50 mm									
	58C	clamping flange Ø 36 mm									
resolution	D	ppr 100 ... 2500 mm									
zero pulse	S	without zero pulse									
	Z	with zero pulse									
power supply	5/30	5...30 Vdc									
electronic interference	P	push-pull									
	L	line driver									
shaft diameter	6	mod. B - mm 6									
	10	mod. C - mm 10									
enclosure rating	X	IP54									
	S	IP66									
option	X	to be reported									
output type	P	cable (standard length 1.5 m)*									
	M	MIL connector									
	M12	M12 connector									
direction type	A	axial									
	R	radial									

\* Longer cable available on demand



Standard Ø 58 mm  
encoder

## technical specification

	MDI 58 B/C
shaft diameter	Ø 6 mod.B Ø 10 mm mod.C
IP mechanical protection	X = IP 54 (IEC 60529) S = IP 66 (IEC 60529)
max rotation speed	6000 rpm (IP54) 3000 rpm / 70° C - 2000 rpm / 85° C (IP66)
max shaft load	10 N axial with Ø6 mm shaft 20 N radial with Ø6 mm shaft 200 N axial / radial
shock resistance	50 G, 11 ms (IEC 60068-2-27)
vibration resistance	10 G, 10 ... 2000 Hz (IEC 60068-2-6)
moment of inertia	1,5 x 10 <sup>-6</sup> kgm <sup>2</sup>
starting torque (at +20°C / +68°F)	< 0,02 Nm (IP 54) < 0,06 Nm (IP 66)
body material	EN-AW 2011 aluminum
shaft material	1.4305 / AISI 303 stainless steel
housing material	PA66 glass fiber reinforced
bearings	2 ball bearings
bearings life	10 <sup>9</sup> revolutions
operating temperature	-25° ... +85°C (-13° ... +185°F)
storage temperature	-25° ... +70°C (-13° ... +158°F)
weight	350 g (12,35 oz)
resolution	from 100 to 2500 ppr
power supply	5/30 = 4,5 ... 30 V DC (reverse polarity protection)
No-Load supply current	800 mW
max load current	20 mA / channel
output type*	push-pull / line driver
max output frequency	220 kHz
counting direction	A leads B clockwise (shaft view)
EMC	IEC 61000-6-2 IEC 61000-6-4

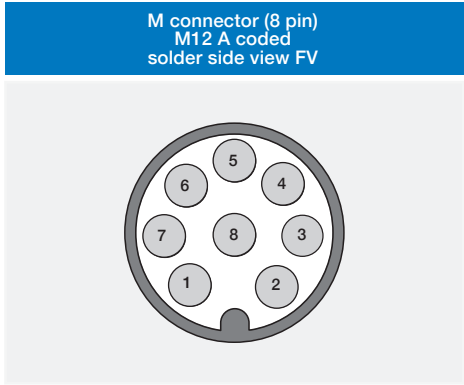
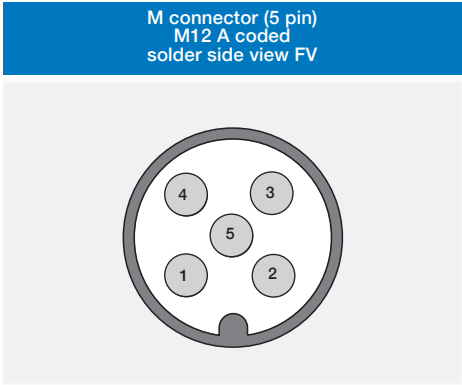
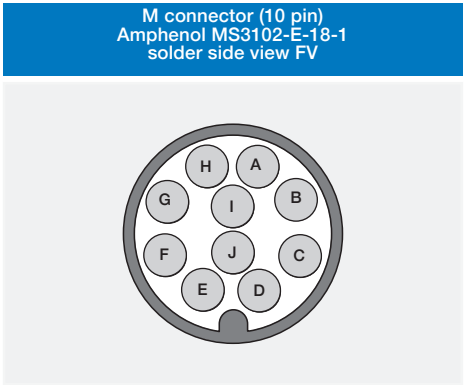
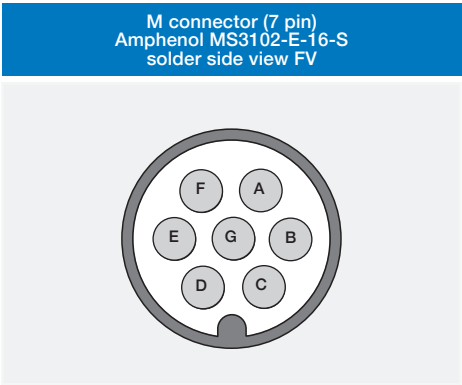
\* output levels according to power supply

## resolutions

MDI 58 B/C
100* - 120 - 128 - 150 - 200 - 240 - 250 - 256 - 300 - 360* - 400* - 480 - 500* - 512* - 600* - 625 - 720* - 750 - 800 - 900 - 1000* - 1024* - 1200 - 1250 - 1440 - 1500 - 1600 - 1800 - 2000* - 2048* - 2500*

\* preferred resolutions

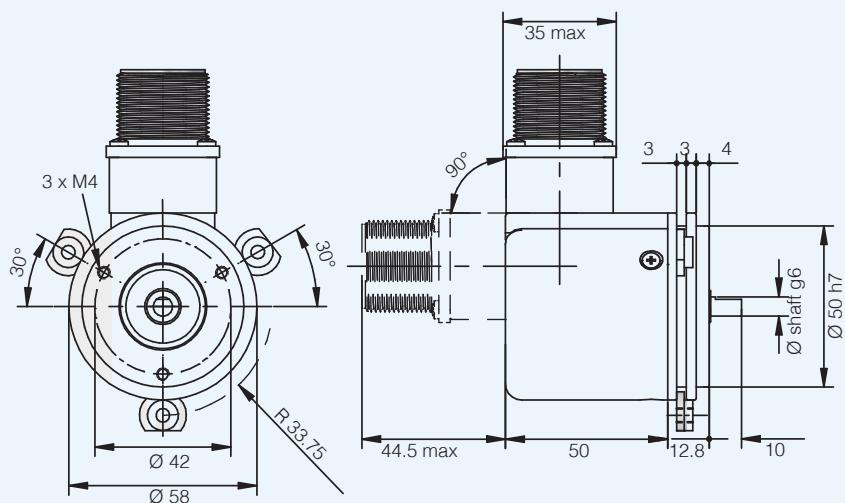
function	Cable output Push pull	Cable output Line driver	7 pin M output Push pull	7 pin M output Line Driver no Zero	10 pin M output Line Driver with Zero	5 pin M12 output Push pull	8 pin M12 output Line Driver
+V DC	red	red	F	D	D - E	2	7
0 V	black	black	A	F	F	4	1
Ch. A	green	green	C	A	A	3	6
Ch. A-	/	brown	/	C	G	/	5
Ch. B	yellow	yellow	E	B	B	1	4
Ch. B-	/	orange	/	E	H	/	3
Ch. Z	blue	blue	D	/	C	5	2
Ch. Z-	/	white	/	/	I	/	8
⏏	shield	shield	G	G	J	housing	housing



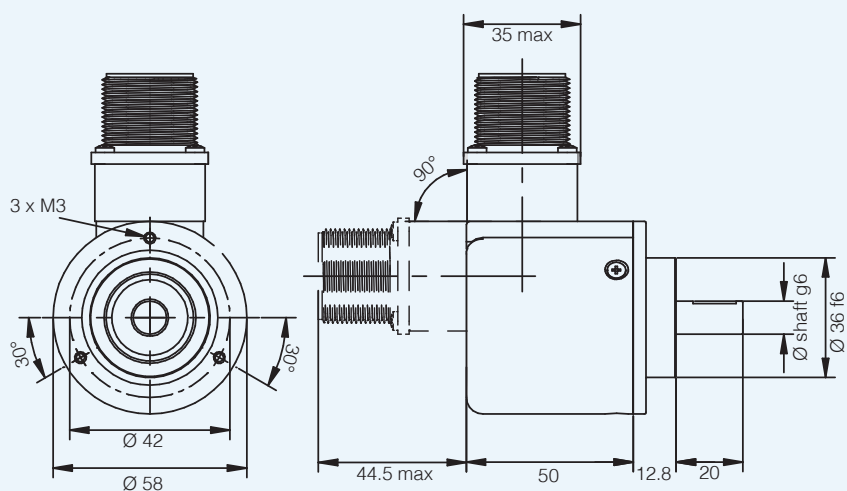


## dimensions (mm)

MDI 58 B

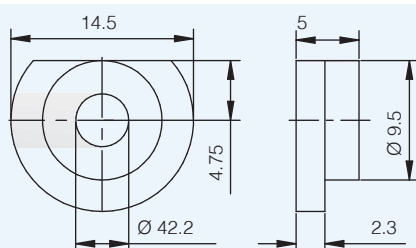


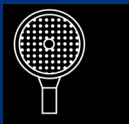
MDI 58 C



## dimensions (mm)

set n.3 fixing clamps for model 58 B





# MDI 63 A / D series

Standard Ø 63 mm encoder series for industrial applications with high mechanical resistance requirements



Standard Ø 63 mm  
encoder

## features

- 3 channel encoder (A / B / Z) up to 2500 ppr
- Power supply up to +30 VDC with several electronic outputs available
- Up to 220 kHz output frequency
- Cable or connector output
- Solid shaft diameter up to 10 mm
- Mounting by synchronous or centering 2,5" square flange



## web contents



- Application notes
- Photos
- Catalogue / Manuals



## code description

	MDI	63A	1000	Z	5/30	P	9	X	X	M	R
series	MDI	incremental encoder series MDI									
model	63A	synchronous flange Ø 31.75 mm									
	63D	centering square flange Ø 31.75 mm									
resolution	D	ppr 100 ... 2500 mm									
zero pulse	S	without zero pulse									
	Z	with zero pulse									
power supply	5/30	5...30 Vdc									
electronic interference	P	push-pull									
	L	line driver									
shaft diameter	9	9,52 (3/8") mm									
	10	10 mm									
enclosure rating	X	IP54									
	S	IP66									
option	X	to be reported									
output type	P	cable (standard length 1.5 m)*									
	M	MIL connector									
	M12	M12 connector									
direction type	A	axial									
	R	radial									

\* Longer cable available on demand

Standard ø 63 mm  
encoder

## technical specification

MDI 63 A / D	
shaft diameter	ø 9,52 (3/8") / 10 mm
IP mechanical protection	X = IP 54 (IEC 60529) S = IP 66 (IEC 60529)
max rotation speed	6000 rpm (IP54) 3000 rpm / 70° C - 2000 rpm / 85° C (IP66)
max shaft load	200 N
shock resistance	50 G, 11 ms up to 2500 ppr (IEC 60068-2-27)
vibration resistance	10 G, 10 ... 2000 Hz (IEC 60068-2-6)
moment of inertia	1,5 x 10 <sup>-6</sup> kgm <sup>2</sup>
starting torque (at +20°C / +68°F)	< 0,02 Nm (IP 54) < 0,06 Nm (IP 66)
body material	EN-AW 2011 aluminum
shaft material	1.4305 / AISI 303 stainless steel
housing material	PA66 glass fiber reinforced
bearings	2 ball bearings
bearings life	10 <sup>9</sup> revolutions
operating temperature	-25° ... +85°C (-13° ... +185°F)
storage temperature	-25° ... +70°C (-13° ... +158°F)
weight	350 g (12,35 oz)
resolution	from 100 to 2500 ppr
power supply	5/30 = 4,5 ... 30 V DC (reverse polarity protection)
No-Load supply current	800 mW
max load current	20 mA / channel
output type*	push-pull / line driver
max output frequency	220 kHz
counting direction	A leads B clockwise (shaft view)
EMC	IEC 61000-6-2 IEC 61000-6-4

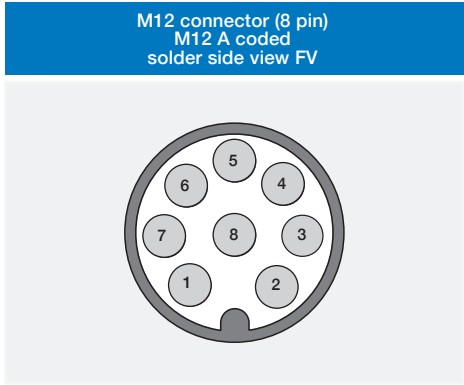
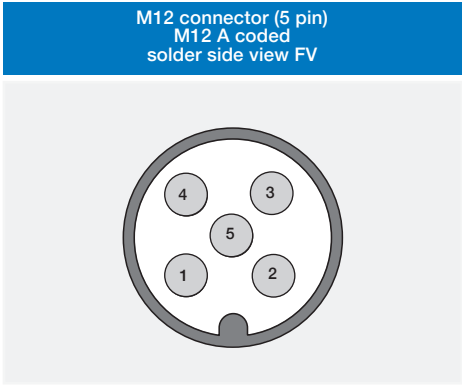
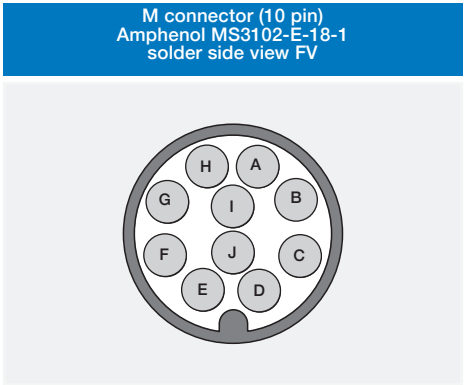
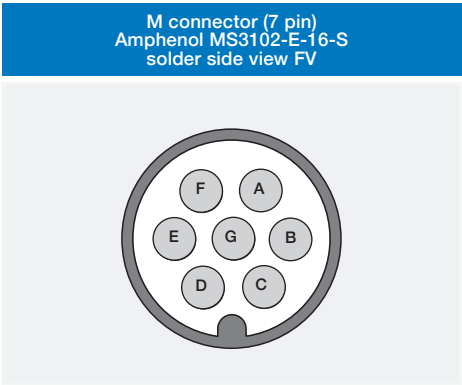
\* output levels according to power supply

## resolutions

MDI 63 A / D
100* - 120 - 128 - 150 - 200 - 240 - 250 - 256 - 300 - 360* - 400 - 480 - 500* - 512* - 600* - 625 - 720* - 750 - 800 - 900 - 1000* - 1024* - 1200 - 1250 - 1440 - 1500 - 1600 - 1800 - 2000* - 2048* - 2500*

\* preferred resolutions

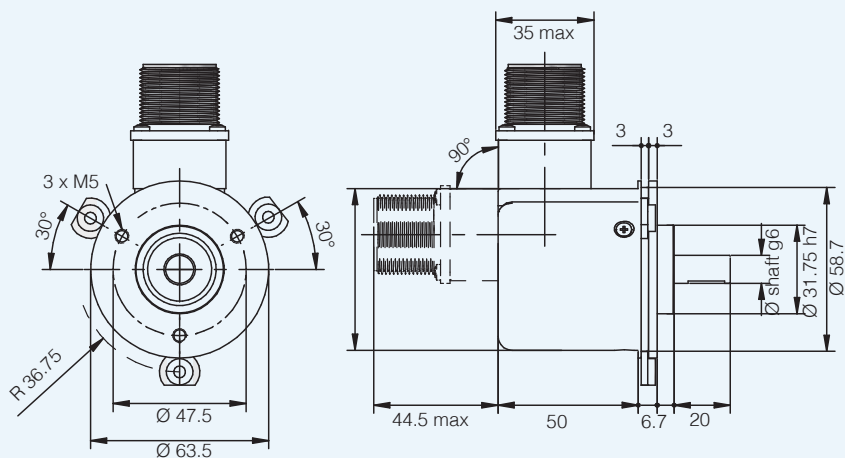
function	Cable output Push pull	Cable output Line driver	7 pin M output Push pull	7 pin M output Line Driver no Zero	10 pin M output Line Driver with Zero	5 pin M12 output Push pull	8 pin M12 output Line Driver
+V DC	red	red	F	D	D - E	2	7
0 V	black	black	A	F	F	4	1
Ch. A	green	green	C	A	A	3	6
Ch. A-	/	brown	/	C	G	/	5
Ch. B	yellow	yellow	E	B	B	1	4
Ch. B-	/	orange	/	E	H	/	3
Ch. Z	blue	blue	D	/	C	5	2
Ch. Z-	/	white	/	/	I	/	8
⏏	shield	shield	G	G	J	housing	housing



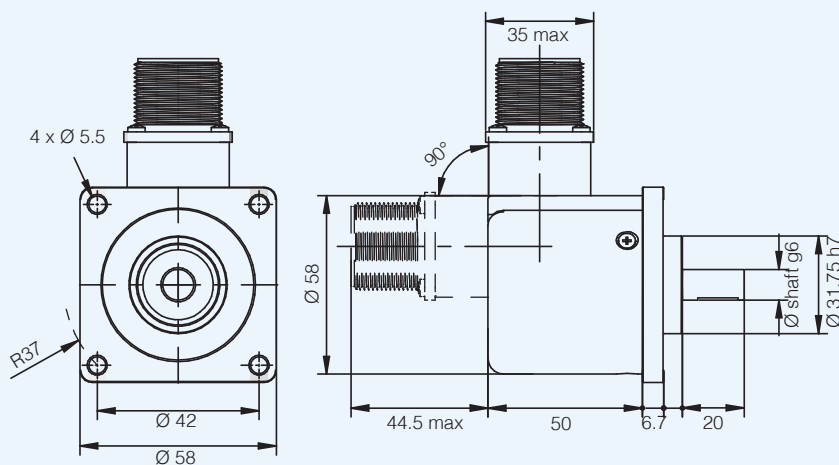


## dimensions (mm)

MDI 63 A

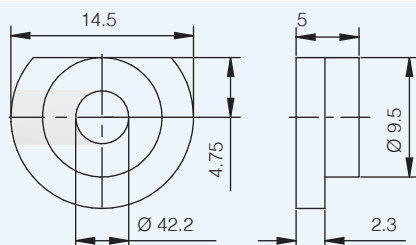


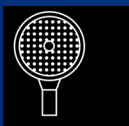
MDI 63 D



## dimensions (mm)

set n.3 fixing clamps for model 63A





# MDI 38 F / G series

Miniaturized ø 38 encoder series for general factory automation applications, small AC motors and gearmotors.



Miniaturized Ø 38 mm  
encoder

## features

- 3 channel encoder (A / B / Z) up to 2500 ppr
- Power supply up to +30 VDC with several electronic outputs available
- Up to 220 kHz output frequency
- Cable output, connectors available on cable end
- Metal cover for high IP mechanical protection
- Blind hollow shaft diameter up to 10 mm
- Mounting by stator coupling or anti-rotation pin



## web contents



- Application notes
- Photos
- Catalogue / Manuals



## code description

	MDI	38F	1024	Z	5/30	P	6	X	X	PR
series	MDI	incremental encoder series MDI								
model	38F	blind hollow shaft with stator coupling								
	38G	blind hollow shaft with anti-rotation pin								
resolution	D	ppr 100 ... 2500 mm								
zero pulse	S	without zero pulse								
	Z	with zero pulse								
power supply	5/30	5...30 Vdc								
electronic interference	P	push-pull								
	L	line driver								
bore diameter	6	6 mm								
	8	8 mm								
	10	10 mm								
enclosure rating	X	IP64								
	S	IP65								
option	X	to be reported								
	PR	radial cable (standard length 0.5 m)*								

\* Longer cable available on demand





## technical specification

	MDI 38 F / G
bore diameter	ø 6* / 8* / 10 mm
IP mechanical protection	IP 64 (IEC 60529) IP 65 (IEC 60529)
max rotation speed	3000 rpm
max shaft load	5 N axial / radial
shock resistance	50 G, 11 ms (IEC 60068-2-27)
vibration resistance	10 G, 10 ... 2000 Hz (IEC 60068-2-6)
moment of inertia	0,8 x 10 <sup>-6</sup> kgm <sup>2</sup>
starting torque (at +20°C / +68°F)	< 0,01 Nm (IP 64) < 0,06 Nm (IP 65)
body material	EN-AW 2011 aluminum
shaft material	1.4305 / AISI 303 stainless steel
housing material	painted aluminum
bearings	2 ball bearings
bearings life	10 <sup>9</sup> revolutions
operating temperature	-20° ... +70°C
storage temperature	-25° ... +70°C
weight	150 g
resolution	from 100 to 2500 ppr
power supply	5/30 = 4,5 ... 30 V DC (reverse polarity protection)
No-Load supply current	800 mW
max load current	20 mA / channel
output type**	push-pull / line driver
max output frequency	220 kHz
counting direction	A leads B clockwise (shaft view)
EMC	IEC 61000-6-2 IEC 61000-6-4

\* with supplied adapter shaft

\*\* output levels according to power supply



function	Cable output Push pull	Cable output Line driver
+V DC	red	red
0 V	black	black
Ch. A	green	green
Ch. A-	/	brown
Ch. B	yellow	yellow
Ch. B-	/	orange
Ch. Z	blue	blue
Ch. Z-	/	white
⏏	shield	shield

resolutions

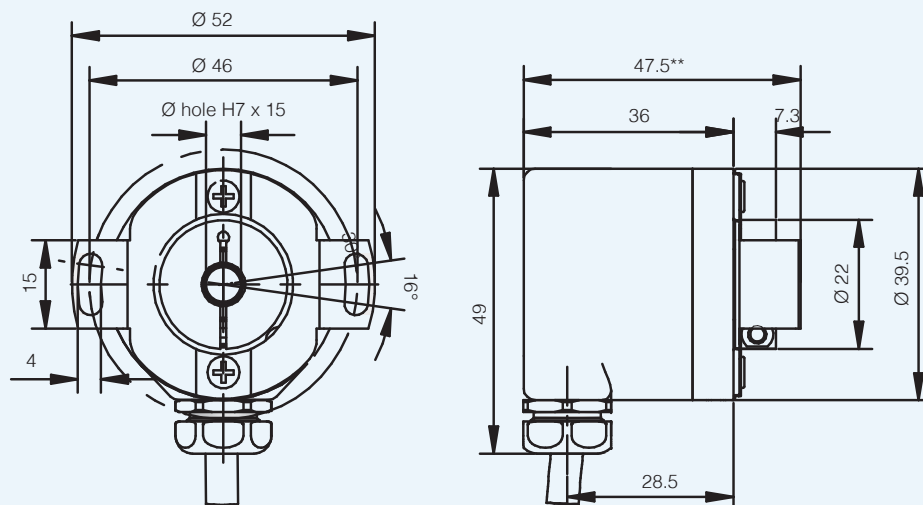
MDI 38 F / G
100* - 120 - 128 - 200 - 240 - 256 - 360* - 400 - 480 - 500* - 512* - 625 - 720 - 750 - 900 - 1000* - 1024* - 1250 - 1440 - 1500 - 1800 - 2000* - 2048* - 2500*

\* preferred resolutions



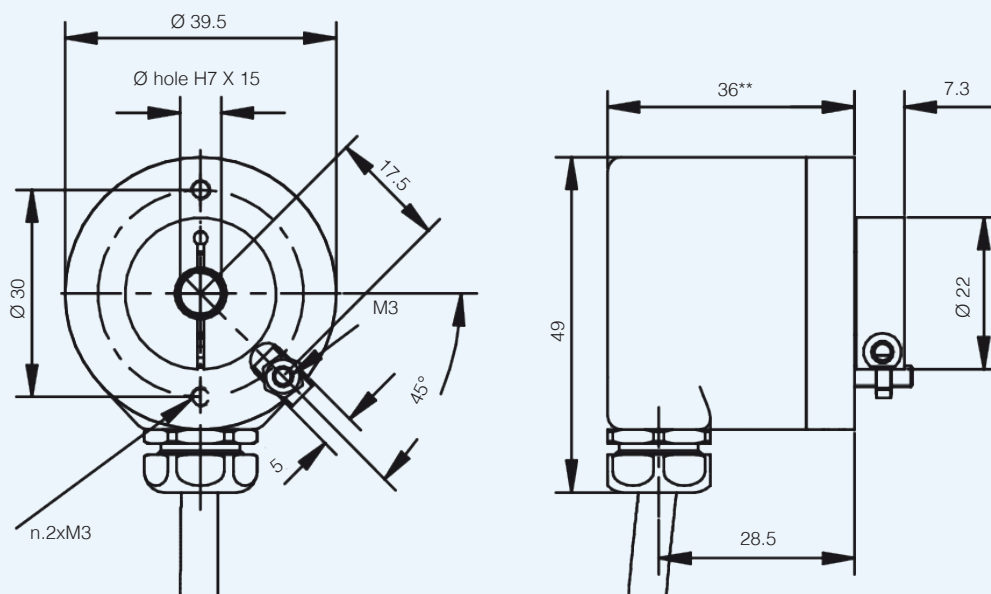
## dimensions (mm)\*

MDI 38 F



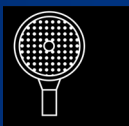
\*\* IP65 + 5.2

MDI 38 G



\*\* IP65 + 5.2

\*anti-rotation pin is included in model G, for mounting instruction please refer to product installation notes



# MDI 58 F / G - 63 F / G series

Hollow shaft encoder series for industrial applications with high mechanical resistance requirements.



Hollow shaft  
encoder series

## features

- 3 channel encoder (A / B / Z) up to 2500 ppr
- Power supply up to +30 VDC with several electronic outputs available
- Up to 220 kHz output frequency
- Cable or connector output
- Blind hollow shaft diameter up to 15 mm
- Mounting by stator coupling, spring or anti-rotation pin



## web contents



- Application notes
- Photos
- Catalogue / Manuals



## code description

	MDI	58G	1000	Z	5/30	P	10	X	X	M	R
series	MDI	incremental encoder series MDI									
model	58F	blind hollow shaft with stator coupling									
	58G	blind hollow shaft with anti-rotation pin									
	63F	blind hollow shaft with spring									
	63G	blind hollow shaft with anti-rotation pin									
resolution	1000	ppr 100 ... 2500 mm									
zero pulse	S	without zero pulse									
	Z	with zero pulse									
power supply	5/30	5...30 Vdc									
electronic interference	P	push-pull									
	L	line driver									
bore diameter	10	10 mm									
	15	15 mm									
enclosure rating	X	IP54									
	S	IP66									
option	X	to be reported									
output type	P	cable (standard length 1.5 m)*									
	M	MIL connector									
	M12	M12 connector									
direction type	A	axial									
	R	radial									

\* Longer cable available on demand



## technical specification


MDI 58 F / G - 63 F / G	
bore diameter	∅ 10 / 15 mm
IP mechanical protection	X = IP 54 (IEC 60529) S = IP 66 (IEC 60529)
max rotation speed	3000 rpm
max shaft load	200 N
shock resistance	50 G, 11 ms up to 2500 ppr (IEC 60068-2-27)
vibration resistance	10 G, 10 ... 2000 Hz (IEC 60068-2-6)
moment of inertia	4 x 10 <sup>-6</sup> kgm <sup>2</sup>
starting torque (at +20°C / +68°F)	< 0,02 Nm (IP 54) < 0,06 Nm (IP 66)
Fixing torque for collar clamping	1 Nm max
body material	EN-AW 2011 aluminum
shaft material	1.4305 / AISI 303 stainless steel
housing material	PA66 glass fiber reinforced
bearings	2 ball bearings
bearings life	10 <sup>9</sup> revolutions
operating temperature	-20° ... +70°C (-4° ... +158°F)
storage temperature	-25° ... +70°C (-13° ... +158°F)
weight	350 g (12,35 oz)
resolution	from 100 to 2500 ppr
power supply	5/30 = 4,5 ... 30 V DC (reverse polarity protection)
No-Load supply current	800 mW
max load current	20 mA / channel
output type*	push-pull / line driver
max output frequency	220 kHz
counting direction	A leads B clockwise (shaft view)
EMC	IEC 61000-6-2 IEC 61000-6-4

\* output levels according to power supply

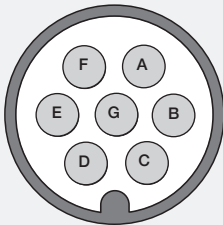
## resolutions

MDI 58 F / G - 63 F / G
100* - 120 - 128 - 200 - 240 - 256 - 360* - 400 - 480 - 500* - 512* - 625 - 720* - 750 - 900 - 1000* - 1024* - 1250 - 1440 - 1500 - 1800 - 2000* - 2048* - 2500*

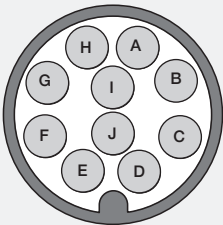
\* preferred resolutions

function	Cable output Push pull	Cable output Line driver	7 pin M output Push pull	7 pin M output Line Driver no Zero	10 pin M output Line Driver with Zero	5 pin M12 output Push pull	8 pin M12 output Line Driver
+V DC	red	red	F	D	D - E	2	7
0 V	black	black	A	F	F	4	1
Ch. A	green	green	C	A	A	3	6
Ch. A-	/	brown	/	C	G	/	5
Ch. B	yellow	yellow	E	B	B	1	4
Ch. B-	/	orange	/	E	H	/	3
Ch. Z	blue	blue	D	/	C	5	2
Ch. Z-	/	white	/	/	I	/	8
	shield	shield	G	G	J	housing	housing

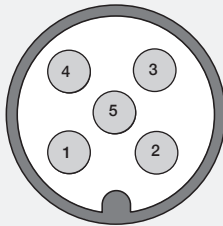
M connector (7 pin)  
Amphenol MS3102-E-16-S  
solder side view FV



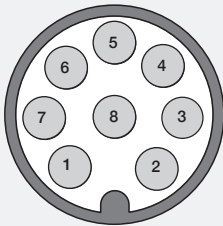
M connector (10 pin)  
Amphenol MS3102-E-18-1  
solder side view FV



M12 connector (5 pin)  
M12 A coded  
solder side view FV



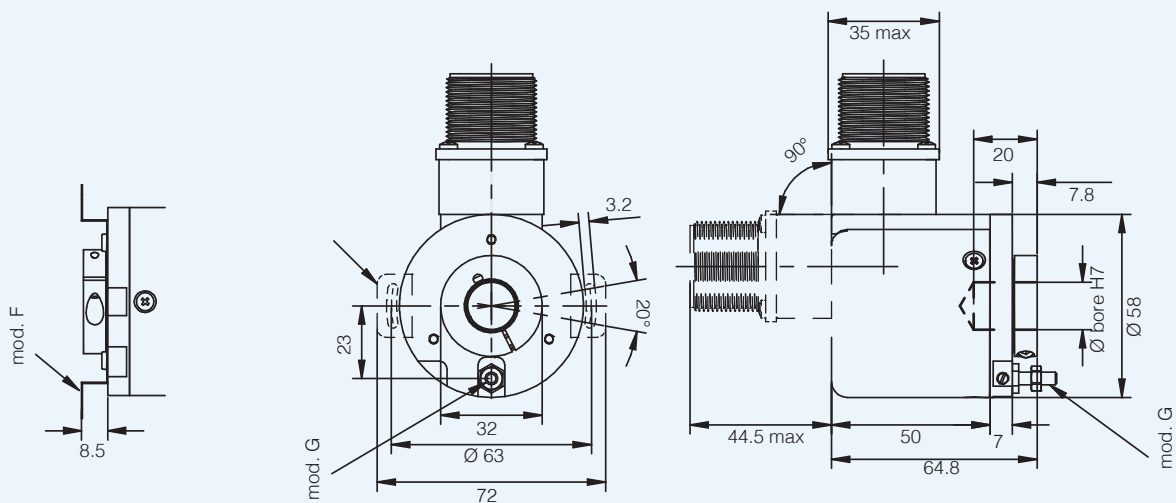
M12 connector (8 pin)  
M12 A coded  
solder side view FV



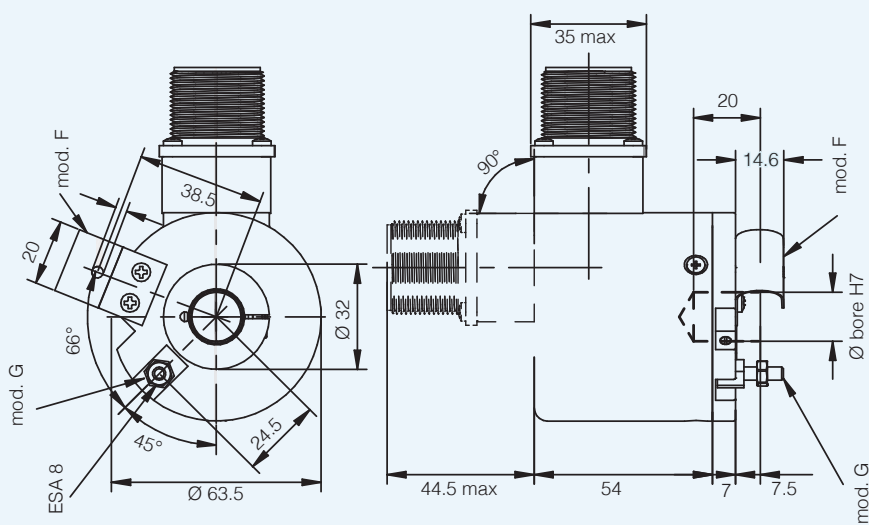


## dimensions (mm)

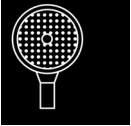
MDI 58 F/G



MDI 63 F/G



anti-rotation pin is included in model G, for mounting instruction please refer to product installation notes



# Elastic Couplings

Essential parts for motion transmission to the encoder shaft.

- aluminium alloy made
- composed by a cylindrical body on which there is a helical groove that determines:
  - torsional rigidity
  - ability to compensate for slight shaft misalignments
  - ability to absorb shaft axial play
- supplied with different coupling diameters

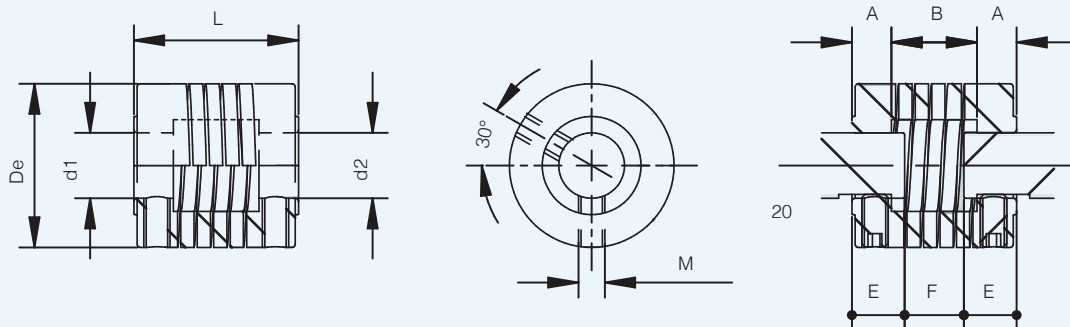
## code description

	MDG	25	A	6	/8
series	MDG	precision elastic coupling			
model	20	(see table) 20			
	25	(see table) 25			
	30	(see table) 30			
shaft fixing type	A	shaft fixing with grub screw			
hole diameter d1	6	ø 6 mm			
	8	(mod. G25 / G30) ø 8 mm			
	9	ø 9,52 (3/8") mm			
	10	ø 10 mm			
hole diameter d2 (do not add if d2 = d1)	6	ø 6 mm			
	8	(mod. G25 / G30) ø 8 mm			
	9	ø 9,52 (3/8") mm			
	10	ø 10 mm			





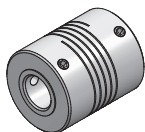
## Elastic Couplings



## standard couplings

Type of material:  
aluminium

For other holes (d1-d2)  
contact our office  
directly



standard couplings	De	L	d1 = d2		A	B	M	E	F	Torque
MDG 20 A 6	ø 20	20	+0.1 -0.1	ø 6H7 +0.012 0	6	8	M3	7	6	0.25 Nm
MDG 25 A 8	ø 25	25	+0.1 -0.1	ø 8H7 +0.015 0	7	11	M4	8	9	0.4 Nm
MDG 25 A 9	ø 25	25	+0.1 -0.1	ø 9,52H7 +0.015 0	7	11	M4	8	9	0.4 Nm
MDG 25 A 10	ø 25	25	+0.1 -0.1	ø 10H7 +0.015 0	7	11	M4	8	9	0.4 Nm
MDG 30 A 10	ø 25	30	+0.1 -0.1	ø 10H7 +0.015 0	8	14	M4	9	12	0.4 Nm

For proper installation it is recommended to insert shafts in the coupling observing "E" dimensions.

